

#### Affiliated to

## DR. A.P.J. ABDUL KALAM TECHNICAL UNIVERSITY, LUCKNOW



## **Evaluation Scheme & Syllabus**

For

Bachelor of Technology

Mechanical Engineering (ME)

Fourth Year

(Effective from the Session: 2023-24)

# NOIDA INSTITUTE OF ENGG. & TECHNOLOGY, GREATER NOIDA, GAUTAM BUDDH NAGAR (AN AUTONOMOUS INSTITUTE)

# **Bachelor of Technology Mechanical Engineering**

### **Evaluation Scheme**

**SEMESTER - VII** 

Sl. No	Subjet	Subject Name	P	erio	ods Evaluation Schemes End Semester		Total	Credit					
•	Codes	, and the second	L	T	P	CT	TA	TOTAL	PS	TE	PE		
		WEEKS COM	PUL	SO	RY I	INDU	CTI	ON PRO	GRA	M			
		Elements of Flexible											
1	AME0701	Manufacturing System	3	0	0	30	20	50		100		150	3
		and Process Engineering											
2		Departmental Elective- V	3	0	0	30	20	50		100		150	3
3		Open Elective-II	3	0	0	30	20	50		100		150	3
4		Open Elective-III	3	0	0	30	20	50		100		150	3
5	AME0751	Model Based System	0	0	2				25		25	50	1
3	MIVILO751	Engineering Lab.	U	U	2				23		23	30	1
6	AME0759	Internship Assessment-III	0	0	2				50			50	1
7		MOOCs (Essential for											
/		Hons. Degree)											
		Total										700	14

#### List of MOOCs (Coursera) Based Recommended Courses for Fourth Year (Semester-VII ) B. Tech Students

S. No.	Subject Code	Course Name University/ Industry Partner Name		N. of Hours	Credits
1.	AMC0169	MBSE: Model-Based Systems Engineering	University at Buffalo, The state University of New York	21	1.5
2.	AMC0154	Cyber Security in Manufacturing	University at Buffalo, The state University of New York	21	1.5

#### **PLEASE NOTE:-**

• Internship (3-4 weeks) shall be conducted during summer break after semester-VI and will be assessed during Semester-VII

### **List of Department Elective :-**

S.No.	Subject Code	Subject Name	Bucket Name	Semester
1	AME0711	Autonomous vehicles	Automotive Engineering	VII
2	AME0712	Smart Manufacturing	Industry 4.0	VII

# NOIDA INSTITUTE OF ENGG. & TECHNOLOGY, GREATER NOIDA, GAUTAM BUDDH NAGAR (AN AUTONOMOUS INSTITUTE)

# **Bachelor of Technology Mechanical Engineering**

## **Evaluation Scheme**

#### **SEMESTER - VIII**

Sl.	Subject	Subject Name	I	Perio	ods	E	valua	tion Scher	nes		nd ester	Total	tal Credit
No.	Codes	, and the second	L	T	P	CT	TA	TOTAL	PS	TE	PE		
1		Open Elective-IV	2	0	0	30	20	50		100		150	2
		Capstone											
2	AME0859	Project/Industrial	0	0	18				200		350	550	10
		Internship											
2		MOOCs (Essential for	0	0	0								
3		Hons. Degree)	U	0	0								
		Total										700	12

#### List of MOOCs (Coursera) Based Recommended Courses for Fourth Year (Semester-VIII ) B. Tech Students

S. No.	Subject Code	Course Name	University/ Industry Partner Name	N. of Hours	Credits
1.	AMC0176	3D Printing Hardware	University of Illinois urbana- Champaign	31	2.5
2.	AMC0196	Roadmap to Success in Digital Manufacturing & Design	University at Buffalo, The state University of New York	18	1

# NOIDA INSTITUTE OF ENGINEERING & TECHNOLOGY, GREATER NOIDA

#### (An Autonomous Institute)

#### **AICTE Guidelines in Model Curriculum:**

A student will be eligible to get Under Graduate degree with Honours only, if he/she completes the additional MOOCs courses such as Coursera certifications, or any other online courses recommended by the Institute (Equivalent to 20 credits). During Complete B.Tech. Program Guidelines for credit calculations are as follows.

- 1. For 6 to 12 Hours = 0.5 Credit
- 2. For 13 to 18 = 1 Credit
- 3. For 19 to 24 = 1.5 Credit
- 4. For 25 to 30 = 2 Credit
- 5. For 31 to 35 = 2.5 Credit
- 6. For 36 to 41 = 3 Credit
- 7. For 42 to 47 = 3.5 Credit
- 8. For 48 and above =4 Credit

For registration to MOOCs Courses, the students shall follow Coursera registration details as per the assigned login and password by the Institute these courses may be cleared during the B. Tech degree program (as per the list provided). After successful completion of these MOOCs courses, the students shall provide their successful completion status/certificates to the Controller of Examination (COE) of the Institute through their coordinators/Mentors only.

The students shall be awarded Honours Degree as per following criterion.

- i. If he / she secures 7.50 as above CGPA.
- ii. Passed each subject of that degree program in the single attempt without any grace.
- iii. Successful completion of MOOCs based 20 credits

	B.TECH FOURTH YEAR			
Course Code	AME0701	L	ΓР	Credit
Course Title	Elements of Flexible Manufacturing System and	3 (	) 0	3
Course Title	Process Engineering	3	, 0	3

#### **Course objective:**

The objective of a course on Flexible Manufacturing Systems (FMS) is to provide students with a comprehensive understanding of the principles, concepts, and applications of flexible manufacturing systems in modern manufacturing environments. FMS is a highly automated production system that integrates various manufacturing processes and components to improve efficiency, productivity, and adaptability in manufacturing operations.

**Pre-requisites:** Knowledge of manufacturing processes & machining centers

#### **Course Contents / Syllabus**

#### UNIT-I Basics of FMS

8 hours

Introduction and classification of FMS, Automated production cycle, Need, concept and measurement of flexibility, Types of flexibilities and its measurement, Economic justification and Functional requirements of FMS, FMS processing and quality assurance equipment, e.g., turning and machining centers, Co-ordinate measuring machines, Cleaning and deburring machines, AMHS equipment, cutting tool and tool management, Future trends of Flexible Manufacturing System.

#### UNIT-II Group Technology

8 hours

Introduction of GT, Part family formation-coding and classification systems; Part-machine group analysis, Methods for cell formation, Use of different algorithms, mathematical programming and graph theoretic model approach for part grouping. Determination of machining parameters: effect of parameters on production rate, cost and surface quality, different approaches, advantages of mathematical approach over conventional approach, solving optimization models of machining processes.

#### **UNIT-III** Data bases in Flexible Manufacturing systems and its implementation

8 hours

Manufacturing data systems, manufacturing data flow, computer-aided design and manufacturing considerations when planning for FMS, Implementation objectives, acceptance testing, Performance goals and expectation, maintenance

#### UNIT-IV Introduction to CAPP

8 hours

Introduction to CAPP: Role of process planning, advantages of conventional process planning over CAPP, Generative CAPP system: Importance, principle of Generative CAPP system. Determination of manufacturing tolerances: Methods of tolerance allocation, sequential approach, integration of design and manufacturing tolerances. Determination of optimal index positions for executing fixed sequence, Ouantitative methods.

#### UNIT-V Material Handling systems & Computer Aided Process Planning

8 hours

Conveyors - AGVs - industrial robots in material handling - AS/RS. Generative and variant types, backward and forward approach, feature based and CAD based CAPP.

#### Course outcome: After completion of course students will be able to

grouping, Cellular vs. FMS production.

CO 1	The understanding about factors responsible for the growth of FMS, FMS types and	
	applications, Economic justification for FMS, Co-ordinate measuring machines, Cleaning	K <sub>2</sub>
	and deburring machines, FMS system support equipment	
CO 2	Ability to know about the concept of GT, Part family formation-coding and classification	
	systems, mathematical programming and graph theoretic model approach for part	K <sub>3</sub>

CO 3	Ability to understand CAPP system: Importance, principle of Generative CAPP system.	K <sub>2</sub>
CO 4	Ability to understand the concept of Quantitative methods, Implementation techniques	K
	for CAPP, criteria for selecting a CAPP system and benefits of CAPP	K <sub>2</sub>
CO 5	Apply materials planning and control techniques to effectively manage the flow of	κ
	materials within the organization	IX3

#### Text books:

- 1. Handbook of Flexible Manufacturing System Editor:Nand K. Jha (Academic Press, San Diego,California
- 2. Automation, Production System & Computer Integrated Manufacturing-Groover (PHI)
- 3. Flexible Manufacturing System Wernecks (Spring- Verlag).
- 4. Flexible Manufacturing Cells and systems W. W.Luggen (PHI)
- 5. CAD/CAM- P. N. Rao(Tata McGraw Hill)
- 6. Mikell P. Groover, Automation, Production systems and Computer Integrated Manufacturing System, Prentice Hall, 2007.

#### **Reference Books:**

- 1. Handbook of Flexible Manufacturing System Editor: Nand K. Jha (Academic Press, San Diego, California).
- 2. Automation, Production System & Computer Integrated Manufacturing-Groover (PHI).
- 3. Performance Modelling of Automated Manufacturing Systems –Vishwanathan&Narahari (PHI)

## **Link:** NPTEL/ YouTube/ Faculty Video Link:

Unit 1	https://onlinecourses.nptel.ac.in/noc21_me83
Unit 2	https://www.youtube.com/watch?v=OG-1Xy1OpUM
Unit 3	https://www.youtube.com/watch?v=kgCMJIVI5XE
Unit 4	https://www.youtube.com/watch?v=20_K7c65Swg
Unit 5	https://www.youtube.com/watch?v=g-zMhN4S8yY

	B.TECH FOURTH YEAR				
Subject Code	AME0751	L	Т	Р	Credit
Subject Name	Model Based System Engineering Lab	0	0	2	1

**Course Objective-** The course aims to provide students with a comprehensive understanding of Model-Based Systems Engineering (MBSE) principles and techniques. Throughout the course, students will delve into various aspects of MBSE, including requirements elicitation and modeling, system architecture design and analysis, behavioral modeling and simulation, trade-off analysis, and decision-making.

Course outcome:	At the end of course, the student will be able to	
CO1	understand of the fundamental principles, methodologies, and best practices of MBSE, including requirements elicitation, system architecture design, and behavioral modeling.	K2
CO2	use MBSE tools and software to create and manage system models, perform analysis and simulations, and facilitate collaboration and communication among team members.	K2
CO3	to apply MBSE techniques, such as use case diagrams, activity diagrams, and requirements diagrams, to effectively capture, model, and analyze system requirements, behavior, and interactions.	K2
CO4	acquire skills in designing and analysing system architectures, performing trade-off analysis, considering factors like cost, performance, reliability, and risk, and making informed design decisions based on MBSE models.	K2
CO5	demonstrate the ability to identify system performance bottlenecks, analyze system behavior, and apply optimization techniques to improve system performance and meet desired requirements. Develop problem-solving skills by addressing real-world challenges in system integration, safety analysis, change management, and validation testing using MBSE approaches	K2

#### **Total No. of Practical**

#### **List of Practical:-**

1	Objective: Elicit system requirements from stakeholders and create a requirements model using MBSE techniques such as use case diagrams, activity diagrams, and requirements diagrams.
2	Objective: Design and analyze the system architecture using MBSE tools, focusing on components, interfaces, and interactions. Perform structural and behavioral analysis of the architecture model.
3	Objective: Model the system behavior using dynamic behavior diagrams (e.g., activity diagrams, statecharts) and simulate the behavior using MBSE tools. Analyze the system performance and validate the model against the desired behavior.
4	Perform trade-off analysis using MBSE models to evaluate and compare different design alternatives. Consider factors such as cost, performance, reliability, and risk to make informed design decisions.
5	Design and execute validation tests based on the system model to ensure that the system meets the specified requirements. Analyze the test results and refine the system model accordingly.
6	Manage system changes using MBSE tools and techniques. Introduce changes to the system model, analyze their impact, and update the model accordingly. Evaluate the effectiveness of the change management process.
7	System Integration and Interface Design Objective: Design and manage system interfaces using MBSE tools. Ensure proper integration and communication between system components. Analyze the impact of interface changes on the system behavior.
8	Analyze the performance of the system model, such as response time, throughput, and resource utilization. Apply optimization techniques to improve system performance and validate the optimized model.
9	Perform safety analysis using MBSE techniques (e.g., fault trees, hazard analysis) to identify potential hazards and mitigate risks. Update the system model to incorporate safety requirements.
10	Collaborate with team members using MBSE tools to enable concurrent engineering, version control, and efficient communication of system design information. Evaluate the effectiveness of collaboration processes.

Course	Code	AME0711	B.TECH FO		L		P	•	Credit
Course Code									
Course Title		Autonomo	us vehicles		3	0	0	3	
To integ technolo vehicles	ogy in ve . To intr	ematic approachicle hardware	ches to self-driven v and software archite t trends and technolo control.	ectures. To dev	elop safet	y assi	ırance	for A	utonomou
	uisites:	<u>-</u>	f AI & logistics. Bas	ics of self-drivir	ig cars &	contro	l syste	ems. Kr	nowledge o
			Course Cont	ents / Syllabus	,				
UNIT-I	Intr	oduction to Self	-Driving Vehicles						8 hours
		=	for Autonomy, Driv and Driving Decisio	-	y, Percept	ion, a	and D	riving	Decisions
UNIT-I			re and Software Arch						8 hour
and Cor	nputing	hardware, hard	Vehicle Hardware, ware computing desi	gn	Environn	nent F	Repres	entatio	1
UNIT-I			r Autonomous Vehicle						8 hour
			rance and testing, sa	fety framework	s for self-	drivir	ıg.		
UNIT-I	·	icle Dynamic M							8 hour
		ig in 2D, Kinema icle Longitudina	tic bicycle model, Dyna	amic modeling in	2D, Latera	al Dyna	amics		1
UNIT-V	/   ven	icie convituaina							0 1
Proporti-	onal-Inte		e (PID), Longitudinal	speed control	with PID,	Feed	forwa	rd spee	
Course	outcome	gral-Derivative	e (PID), Longitudinal	ents will be ab		Feed	forwa	rd spee	ed control.
Course CO 1	outcome Unders	gral-Derivative  : After completand the concept	e (PID), Longitudinal etion of course stude t of self-driven vehicles	ents will be ab	le to	Feed	forwa	rd spee	ed control.
Course CO 1	outcome Unders Explain	gral-Derivative  : After completand the concept the basic concept	e (PID), Longitudinal etion of course stude t of self-driven vehicles ots of hardware and so	ents will be ab	le to	Feed	forwa	rd spee	K <sub>3</sub>
Course CO 1	outcome Unders Explain Know o	gral-Derivative  : After completand the concepthe basic concept the safety assuments.	e (PID), Longitudinal etion of course stude t of self-driven vehicles	ents will be ables.  ftware architects vehicles.	le to			rd spee	K <sub>3</sub>
Course CO 1 CO 2 CO 3	outcome Unders Explain Know o	gral-Derivative  : After completand the concept the basic concept the safety assumed and and explain	e (PID), Longitudinal etion of course stude t of self-driven vehicles ots of hardware and so urance for Autonomou	ents will be ables.  ftware architects vehicles.  nology in vehicle	le to ures.			rd spee	K <sub>3</sub> K <sub>3</sub>
Course CO 1 CO 2 CO 3 CO 4 CO 5	Outcome Unders Explain Know o Unders	gral-Derivative  : After completand the concept the basic concept the safety assumed and and explain	e (PID), Longitudinal etion of course stude t of self-driven vehicles ots of hardware and so urance for Autonomoulatest trends and tech	ents will be ables.  ftware architects vehicles.  nology in vehicle	le to ures.			rd spee	K <sub>3</sub> K <sub>3</sub> K <sub>4</sub>
Course CO 1 CO 2 CO 3 CO 4 CO 5 Text boot 1. Autor 2. Autor	Outcome Unders Explain Know o Unders Unders oks:	gral-Derivative  After complete and the concept the basic concept the safety assumed and explain the concept the c	e (PID), Longitudinal etion of course stude t of self-driven vehicles ots of hardware and so urance for Autonomoulatest trends and tech	ents will be ables.  ftware architect s vehicles.  mology in vehicle gitudinal control	le to ures. e dynamic			rd spee	K <sub>3</sub> K <sub>3</sub> K <sub>4</sub>
Course CO 1 CO 2 CO 3 CO 4 CO 5 Text bool 1. Autom 2. Autom Referen	outcome Unders Explain Know o Unders Unders oks: nomous V mated Dr nce Book	gral-Derivative  : After completand the concept the basic concept the safety assumed and and explain the concept t	etion of course student of self-driven vehicles ots of hardware and sourance for Autonomoulatest trends and technologies are designed to the self-driven vehicle lonerated to vehicle lonerated to System	ents will be ables.  ftware architect s vehicles.  Inology in vehicle gitudinal control ge) s by Tom Dente	le to ures. e dynamic	model		rd spee	K <sub>3</sub> K <sub>3</sub> K <sub>4</sub>
Course CO 1 CO 2 CO 3 CO 4 CO 5 Text bool 1. Auton Referen Autonon	Outcome Unders Explain Know o Unders Unders oks: nomous Ven mous Ven	gral-Derivative  : After complete and the concept the basic concept the safety assumed and explain the concept the concept the concept the concept the safety assumed the concept the conc	etion of course student of self-driven vehicles ots of hardware and sourance for Autonomoulatest trends and technology to the self-driven vehicle lone of the	ents will be ables.  ftware architect s vehicles.  Inology in vehicle gitudinal control ge) s by Tom Dente	le to ures. e dynamic	model		rd spee	K <sub>3</sub> K <sub>3</sub> K <sub>4</sub>
Course CO 1 CO 2 CO 3 CO 4 CO 5 Text boot 1. Auton 2. Auton Referen Autonor Link: N	outcome Unders Explain Know o Unders Unders oks: nomous Venated Dr ce Book mous Vel	gral-Derivative  E: After complete and the concept the basic concept the basic concept and and explain and the concept and the	etion of course student of self-driven vehicles ots of hardware and sourance for Autonomoulatest trends and technic related to vehicle lonemitrakopoulos Georger Assistance System	ents will be ables.  ftware architect s vehicles.  Inology in vehicle gitudinal control ge) s by Tom Dente	le to ures. e dynamic	model		rd spee	K <sub>3</sub> K <sub>3</sub> K <sub>4</sub>
Course CO 1 CO 2 CO 3 CO 4 CO 5 Text boot 1. Autom 2. Autom Referen Automore Link: N Unit 1	outcome Unders Explain Know o Unders Unders oks: nomous Ven mated Dr ce Book mous Ven PTEL/ Y	gral-Derivative  E: After complete and the concept the basic concept the basic concept the basic concept the safety assumed and explain the concept the concept the basic conc	etion of course student of self-driven vehicles of hardware and sourance for Autonomoulatest trends and technologies are designed assistance System Driving by Ronald Key Video Link:	ents will be ables.  ftware architect s vehicles.  inology in vehicle gitudinal control ge) s by Tom Dent  K. Jurgen, SAE	le to ures. e dynamic	model	ing		K <sub>3</sub> K <sub>3</sub> K <sub>4</sub> K <sub>3</sub>
Course CO 1 CO 2 CO 3 CO 4 CO 5 Text bool 1. Auton 2. Auton Referen Autonom Link: N Unit 1 Unit 2	outcome Unders Explain Know o Unders Unders Oks: nomous Venter Book mous Venter PTEL/Y https: dex=	gral-Derivative  E: After complete and the concept the basic concept the basic concept the safety assumed and explain the concept the concept the safety assumed and the concept the conce	etion of course student of self-driven vehicles of hardware and sourance for Autonomoulatest trends and technical trelated to vehicle lonemitrakopoulos Georger Assistance System  Driving by Ronald For the Video Link:  otel.ac.in/noc21_me83	ents will be ables.  ftware architect s vehicles.  inology in vehicle gitudinal control ge) s by Tom Dente K. Jurgen, SAE	le to ures. e dynamic	model	ing		K <sub>3</sub> K <sub>3</sub> K <sub>4</sub> K <sub>3</sub>
Course CO 1 CO 2 CO 3 CO 4 CO 5 Text bool 1. Auton Referen Autonom	outcome Unders Explain Know o Unders Unders Oks: nomous V nated Dr ce Book nous Vel PTEL/Y https: dex= https:	gral-Derivative  : After complete and the concept the basic concep	etion of course student of self-driven vehicles of self-driven and so urance for Autonomous latest trends and technot related to vehicle lone of the self-driven by Ronald For the self-dr	ents will be ables.  ftware architect s vehicles.  inology in vehicle gitudinal control ge) s by Tom Dent K. Jurgen, SAE  R_0&list=PL_GR	le to  ures.  e dynamic i  on  Internatio	model nal	ing 9bO85.	Ab2fES7	K <sub>3</sub> K <sub>3</sub> K <sub>4</sub> K <sub>3</sub>

	B.TECH FOURTH YEAR				
<b>Course Code</b>	AME0712	L	T	P	Credit
<b>Course Title</b>	Smart Manufacturing	3	0	0	3

#### Course objective:

This course is intended to make the students learn the fundamentals of digital twins, including their types, benefits, challenges, and best practices. Also, the understanding of the various components of a smart factory and the role they play in optimizing the production process, principles and techniques used to design, analyze, and implement Cyber Physical Systems. connected manufacturing, which is the integration of digital technology into industrial processes and lastly the fundamental principles and methods used in cognitive systems.

#### **Pre-requisites:**

UNIT-I

#### **Course Contents / Syllabus**

Introduction - Definition and history of digital twins, Types of digital, Applications of digital twins in various industries. Benefits of digital twins, Challenges of digital twins. Tools and Techniques - Digital twin software and platforms, Data acquisition and integration techniques, Modeling and simulation techniques. Applications in Industry - Digital twins in manufacturing, Digital twins in healthcare, Digital twins in construction. Miscellaneous - Ethical, Legal, and Social Implications of Digital Twins, Future of

Digital twins, Emerging Trends and Opportunities, Implications for society and the economy.

#### **UNIT-II** Self-Driving Hardware and Software Architectures

8 hours

8 hours

Introduction - Definition of smart factory, Historical perspective of manufacturing, Key drivers for smart factory implementation, Components of smart factory. Architecture of Smart Factory - Layers of smart factory architecture, Communication protocols in smart factory, Cloud computing and edge computing in smart factory. Benefits of Smart Factory - Increased productivity, Enhanced quality, Improved safety, Better flexibility and customization, Reduced costs. Challenges and Risks - Data security and privacy concerns, Workforce reskilling and training, Integration with legacy systems, Initial costs and Return on Investment.

#### **UNIT-III** Cyber Physical Systems

**Digital Twins** 

8 hours

Introduction - Definition of CPS, Historical development and current trends, Examples of CPS applications. **Devices used in CPS** - Sensors and Actuators, Sensor fusion and data integration, Actuator control and feedback, PID controllers, Model-based control. **Real-Time Systems** - Real-time scheduling, Deadline analysis, Timing analysis. **Networking for CPS** - Wired and wireless networks, Network protocols for CPS, Quality of Service (QoS) in CPS. **Security** and Privacy challenges in CPS. **Future trends** and Opportunities in CPS.

#### UNIT-IV Connected Manufacturing

8 hour

Introduction – Definition, History and evolution of connected manufacturing, Key components of connected manufacturing, Benefits of connected manufacturing. IoT and Connected Devices - Overview of IoT and its applications in industrial settings, Sensors and connected devices in manufacturing, Security and privacy considerations. Artificial Intelligence - Applications of AI in manufacturing, Use of AI for predictive maintenance and quality control. Data Analytics and Cloud Computing - Overview of data analytics and its applications in industrial settings, Use of cloud computing for data storage and processing, Real-time data analytics and its impact on manufacturing processes. Future of connected manufacturing.

#### UNIT-V Cognitive Systems

8 hours

Introduction - Overview of the field of cognitive systems, Historical background, Key challenges in cognitive systems. Cognitive Architectures - Introduction to cognitive architectures, Comparison of different architectures. Perception and Attention - Overview, Models of visual and auditory perception,

Attention and its role in cognition. Memory and Learning - Introduction to memory and learning in cognitive systems, Models of human memory and learning. Decision-Making - Overview of decision-making in cognitive systems, Rational and heuristic decision-making models. Natural Language Processing - Introduction to natural language processing in cognitive systems, Models of syntax and semantics. Case Studies: Cognitive systems in real-world applications (e.g., robotics, human-computer interaction), Discussion of ethical and social implications of cognitive systems.

#### Course outcome: After completion of course students will be able to

CO 1	Define the concept of digital twins and identify their types and applications.	К2
CO 2	Define the concept of a smart factory and its various components and Understand the	К2
	architecture of a smart factory	
CO 3	Understand the fundamental principles and concepts of Cyber-Physical Systems	К2
CO 4	Define connected manufacturing and understand its various components and analyze its	К2
	impact on industrial processes.	
CO 5	Understand the key concepts and theories in cognitive systems research	К2

#### **Text books:**

- 1. "Industry 4.0: The Industrial Internet of Things" by Alasdair Gilchrist, published by Wiley.
- 2. "Smart Factory: Concepts and Technologies" by Liang Xu, Jiafu Wan, and Hong Wang, published by Springer.
- 3. "Digital Twin Technologies and Smart Cities" by Subhasish Dasgupta, published by CRC Press

#### **Reference Books:**

- 1. "Cyber-Physical Systems: From Theory to Practice" by Rajeev Alur and Insup Lee, published by The Institution of Engineering and Technology (IET)
- 2. "Cognitive Systems: Human Cognitive Models in Systems Design" by Chris Forsythe and Wayne Gray, published by Psychology Press.

#### Link: NPTEL/ YouTube/ Faculty Video Link:

Unit 1	(207) What is a Digital Twin? - YouTube
Unit 2	(207) Industry 4.0 - "Smart Factory" explained - YouTube
Unit 3	Introduction to Cyber-Physical Systems - YouTube
Unit 4	Connected Manufacturing webinar recording - YouTube
Unit 5	(207) Cognitive Systems Colloquium Introduction - YouTube